# 'Atomic' Development environment for customized applications





# Introduction

- Atomic is a micro programming language designed for the 'full digital' EVER SDM, MD, SW and SM family drives.
- The scope of this language is to give the user the freedom to create his own simple application without having to switch to more complex and more expensive drives.
- ✓ Atomic's philosophy is to have few but powerful instructions.
- The programming of Atomic is done by means of user friendly Personal Computer with the Atomic environment and an SDM, MD, SW or SM drives with 'Atomic Ready' logo and Atomic firmware (c0499).



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### Hardware - Software components

#### Hardware and software components table compatible with 'Atomic':

| Drives                                                                                                                                                                                                                | Software kit |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|
| - SDMWD180vA133c0499 - SDMWD180vA143c0499<br>- SDMWA180vA133c0499<br>- SDMWT180vA133c0499                                                                                                                             | SDM_ATM-00   |
| - SDMWD170vB231c0499 - SDMWD170vB242c0499<br>- SDMWA170vB231c0499 - SDMWA170vB242c0499<br>- SDMWA170v2231c0499 - SDMWA170v2242c0499<br>- SDMWA170v4231c0499 - SDMWA170v4242c0499                                      | SDM_ATM-00   |
| - SDMWA130vA136c0499                                                                                                                                                                                                  | S130_ATM-00  |
| <ul> <li>MDK3AxxxNvPA36c0499</li> <li>MDK3BxxxNvPA36c0499</li> <li>MDK3BxxxNvPA36c0499</li> <li>MDK3CxxxNvPA36c0499</li> <li>MDK3CxxxNvPA36c0499</li> <li>MDK3DxxxNvPA36c0499</li> <li>MDK3DxxxHvPA36c0499</li> </ul> | MD_ATM-00    |
| - SW1D4080N361-00c0499                                                                                                                                                                                                | SW_ATM-00    |
| - SM2Ax60PNx43Ax0c0499 - SM2Ax60PNx43Bx0c0499<br>- SM2Ax60PNx43Dx0c0499 - SM2Ax60PNx43Ex0c0499                                                                                                                        | SM_ATM-00    |

#### The software kits include:

- the CD ATOMIC to install the PC environment
- the **RS232 cable** adapted to the requested drives

### **Technical specifications**

✓ These are the specifications and the supported application functions :

- 15 powerful macro instructions
- 8 storable user applications
- 640 bytes of max program size
- 6 bytes of medium length instructions
- 32 user variables
- Supports 4 bytes integer numbers
- Access to all the controlling objects of the drives
- Access to all the I/O's of the drives
- Multitasking support up to 8 user tasks
- A medium execution time of <1 ms per instruction</p>

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### Atomic advantages

Atomic introduces a new way to create an own application:

- Simple, fast and complete building of the user's cycle
- A broad versatility for different application requirements
- The user doesn't have to learn the instructions syntax
- Functions on all drives of the SDM, MD, SW and SM series with c0499 firmware
- Integrates all advantages of the f<sup>4</sup>d<sup>2</sup> technology
- Simplifies the debugging of the application
- It benefits from all the power of the DSP's integrated in the drives
- Complete support and training by EVER Elettronica's support dept.

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Motor handling instructions:

| Instruction                                                    | Description                      | Parameters                                            |
|----------------------------------------------------------------|----------------------------------|-------------------------------------------------------|
|                                                                |                                  | 1) Type of movement (steps/target/homing).            |
| MOVE (1) Starts the motor according<br>to the given parameters |                                  | 2) [optional] Movement Parameter (steps #, position). |
|                                                                | 3) [optional] Profile velocity.  |                                                       |
|                                                                |                                  | 4) [optional] Acceleration ramp.                      |
|                                                                | 5) [optional] Deceleration ramp. |                                                       |
|                                                                | Stops the motor according        | 1) Type of stop (no ramp, with ramp, with steps).     |
| SIUP                                                           | to the given parameters          | 2) [optional] Stop parameter (# of steps).            |

(1) The functionality of these instructions is the same as in the CANopen/Modbus SDM drives.

#### Arithmetical instructions:

| Instruction | Description                                                                                                                         | Parameters                                                                          |
|-------------|-------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|
|             | Performs an addition between two                                                                                                    | 1) Destination (User Variable/Object).                                              |
| ADD         | constants) storing the result into an<br>(objects/user variable)<br>Destination = 1 <sup>st</sup> operand + 2 <sup>nd</sup> operand | 2) First Operand (Numerical Constant, User Variable, Object).                       |
|             |                                                                                                                                     | <ol> <li>Second Operand (Numerical Constant, User Variable,<br/>Object).</li> </ol> |
|             | Performs a subtraction between two                                                                                                  | 1) Destination (User Variable/Object).                                              |
| SUB         | constants) storing the result into an                                                                                               | 2) First Operand (Numerical Constant, User Variable, Object).                       |
|             | (objects/user variable)<br>Destination = 1 <sup>st</sup> operand - 2 <sup>nd</sup> operand                                          | <ol> <li>Second Operand (Numerical Constant, User Variable,<br/>Object).</li> </ol> |
|             | Performs a multiplication between two<br>(objects/user variables/numerical<br>constants) storing the result into an                 | 1) Destination (User Variable/Object).                                              |
| MUL         |                                                                                                                                     | 2) First Operand (Numerical Constant, User Variable, Object).                       |
|             | Destination = 1 <sup>st</sup> operand * 2 <sup>nd</sup> operand                                                                     | <ol> <li>Second Operand (Numerical Constant, User Variable,<br/>Object).</li> </ol> |
|             | Performs a division between two                                                                                                     | 1) Destination (User Variable/Object).                                              |
| DIV         | constants) storing the result into an                                                                                               | 2) First Operand (Numerical Constant, User Variable, Object).                       |
|             | (objects/user variable)<br>Destination = 1 <sup>st</sup> operand / 2 <sup>nd</sup> operand                                          | 3) Second Operand (Numerical Constant, User Variable,<br>Object).                   |

**Application flow control instructions:** 

| Instruction | Description                                                               | Parameters                                                            |
|-------------|---------------------------------------------------------------------------|-----------------------------------------------------------------------|
|             | Arrests the user application execution                                    | 1) Event (Time delay, Motor running/at standstill, Input open/close). |
|             | until the specified event occurs                                          | 2) [optional] Time, input #.                                          |
|             |                                                                           | 1) Type of Test (Input open/close, Object/User<br>Variable < > = !=). |
| TEST        | Changes the next instruction pointer<br>depending on the test result<br>4 | 2) Object/User Variable.                                              |
| ILJI        |                                                                           | 3) [optional] Comparison Value.                                       |
|             |                                                                           | 4) Line number if the test result is true.                            |
| JUMP        | Changes the next instruction pointer                                      | 1) Line number.                                                       |
| CONTEX      | Switches to a different user                                              |                                                                       |
| _SWITCH     | application stored in the drive                                           | 1) Application number.                                                |
| END         | End of user application                                                   | None.                                                                 |

#### Set instructions:

| Instruction                                | Description | Parameters                                              |  |
|--------------------------------------------|-------------|---------------------------------------------------------|--|
| CET Sets the destination equal to the sour |             | 1) Destination (User Variable, Object, Digital Output). |  |
| JLI                                        |             | 2) Source (Constant value, User Variable or Object).    |  |

#### **Boolean instructions:**

| Instruction | Description                        | Parameters                                                   |
|-------------|------------------------------------|--------------------------------------------------------------|
|             | Derforme a Peoleon Operation       | 1) Destination (User Variable, Object).                      |
| BOOL        | (AND, OR, Shift Right, Shift Left) | 2) First operand (User Variable or Object).                  |
|             | <b>.</b>                           | 3) Second operand (Constant value, User Variable or Object). |

### **Application** execution

#### At switch-on the SDM drive:

- retrieves the startup parameters (Settings, motor currents, ramps...) stored in NVRAM checking if a valid user application is stored;
- starts the program execution from the first line.

#### During the normal functioning the drive:

- **runs** the user application;
- continues to act as a CANopen/MODBUS standard slave and all the checkings enabled in the 'Drive\_Working\_Settings' object are active.
- **detects** if there is an emergency condition (hardware or software), in this case the user application is arrested until the emergency situation is cleared.

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### Language syntax introduction

The Atomic software development environment is a Microsoft Windows<sup>(tm)</sup> application that enables to build the user application by means of wizards and dialog boxes so it will not be necessary to write a single line of instruction.



This means that the user doesn't have to learn the syntax of the Atomic instructions that are completely handled by the Personal Computer software.

The configuration windows have been designed in order to achieve a fast compilation time and to offer versatile instructions.

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? Help

# System diagnostic

The diagnostic button opens the following window:

| Drive Information | ns Drive VO   | Drive Status    | Drive Register | Drive Alarms  | X Cancel     |                              |
|-------------------|---------------|-----------------|----------------|---------------|--------------|------------------------------|
| Drive Model:      | SDMWD180V     | A133            | Serial Number: | FFFFFFFH      | <u>H</u> elp | Information at the system in |
| Firmware:         | WPW04_499     | V 1.22r00       | Checksum:      | 10BDH         |              |                              |
| Boot:             | WPW04BOOT     | 01 2.0          | Checksum:      | CD36H         |              |                              |
| User Version:     | Atomic Interp | reter V 0.40r00 |                |               |              |                              |
| Temperature:      | 26 •          | с               |                |               |              |                              |
| Voltage:          | 70 \          | /dc             |                |               |              |                              |
|                   |               |                 |                |               |              |                              |
|                   |               |                 | -              |               | ~            |                              |
|                   |               |                 | l              | U Reset Drive |              |                              |

# System configuration

Thanks to the following window it is possible to set the start drive parameters:

| A                      | omic Application Global Parameters                                            |                                                                         |                |
|------------------------|-------------------------------------------------------------------------------|-------------------------------------------------------------------------|----------------|
|                        | VO Settings Miscellaneous Settings<br>Motor Settings Feedback/Impact Settings | User Settings Tasks Settings<br>Electric Gear Settings Working Settings | ✓ OK           |
|                        | Parameter                                                                     | Value                                                                   |                |
|                        | Motor_Step_Angle                                                              | 8                                                                       | ? <u>H</u> elp |
|                        | Motor_Poles                                                                   | 50                                                                      |                |
|                        | Min_Current (mA)                                                              | 0                                                                       |                |
| -                      | Max_Current (mA)                                                              | 5000                                                                    |                |
| Tab that shows the     | Boost_Current (mA)                                                            | 5000                                                                    |                |
| start drive parameters | Nominal_Current (mA)                                                          | 5000                                                                    |                |
|                        | Min_Profile_Velocity (Hz)                                                     | 200                                                                     |                |
|                        | Max_Profile_Velocity (Hz)                                                     | 10000                                                                   |                |
|                        | Profile_Velocity (Hz)                                                         | 2500                                                                    |                |
|                        | Profile_Acceleration (ms)                                                     | 500                                                                     |                |
|                        | Profile_Deceleration (ms)                                                     | 500                                                                     |                |
|                        | Motor_Start_Delay                                                             | 0                                                                       |                |
|                        | Motor_Start_Delay_Pulses                                                      | 0                                                                       |                |
|                        | Motor_Stop_Trigger_Count                                                      | 0                                                                       |                |
| -                      | Read Swrite Read                                                              | Default Values                                                          | &<br>]         |

# System configuration

Thanks to the following window it is possible to set the start drive parameters:

| VO Settings Miscellaneous Settings                                                                                                                                                                                                                                                                                                                                                                                                                                                      | User Settings Tasks                                                                                                                                                                                   | s Settings                                         |                                         |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------|-----------------------------------------|
| Motor Settings Feedback/Impact Settings E                                                                                                                                                                                                                                                                                                                                                                                                                                               | Electric Gear Settings Worki                                                                                                                                                                          | king Settings                                      |                                         |
| <ul> <li>Forward Limit Switch Check</li> <li>Backward Limit Switch Check</li> <li>Fast Stop from Input</li> <li>Limit Switches Motor Action</li> <li>Motor Feedback Check</li> <li>Motor Impact Check</li> <li>Automatic Motor Current Reduction</li> <li>Disable Digital Outputs Firmware Handling</li> <li>Fast Stop Power Action</li> <li>Fast Stop Power Action</li> <li>Motor Rotation Direction</li> <li>Motor Electric Gear Init</li> <li>Motor Feedback Error Action</li> </ul> | Emergency Handling<br>Change Digital Outputs<br>1 2 3 4 5 6 7<br>Abort Application Exec<br>Wait Alarm Reset from<br>B0_In0 V<br>Wait Alarm Reset from<br>Auto Restore Alarm<br>Reset Application Exec | s<br>7<br>cution<br>om Input<br>om PLC<br>kecution | Tab to set the star<br>drive parameters |
| Master Watchdog Timeout Action Drive_Working_Settings: 2112 (0840H) Read Write                                                                                                                                                                                                                                                                                                                                                                                                          | Default Values                                                                                                                                                                                        |                                                    | >                                       |

# System configuration

#### Other utility windows:

| Variable #         | Alias       |              | Starting Value | ^   | <u>v</u> <u>o</u> k |
|--------------------|-------------|--------------|----------------|-----|---------------------|
| User_Long_Var[0]   | Input_Mask  |              | 0              |     | Can                 |
| User_Long_Var[1]   | Position0   |              | 1000           |     | <u> </u>            |
| User_Long_Var[2]   | Position1   |              | 2000           |     | 🤋 <u>H</u> elp      |
| User_Long_Var[3]   | Position2   |              | 3000           |     |                     |
| User_Long_Var[4]   | Position3   |              | 4000           |     |                     |
| User_Long_Var[5]   | Position4   |              | 5000           |     |                     |
| User_Long_Var[6]   | Position5   |              | 6000           |     |                     |
| User_Long_Var[7]   | Position6   |              | 7000           |     |                     |
| User_Long_Var[8]   | Position7   |              | 8000           |     |                     |
| User_Long_Var[9]   |             |              | 0              |     |                     |
| User_Long_Var[10]  |             |              | 0              |     |                     |
| User_Long_Var[11]  |             |              | 0              |     |                     |
| User_Long_Var[12]  |             |              | 0              |     |                     |
| User_Long_Var[13]  |             |              | 0              | ~   |                     |
| 🖉 <u>R</u> ead All | ǿ Write All | Store in NVR | IAM            |     | •                   |
|                    |             | Window t     | o manage       | the |                     |

Window to control the user's application language syntax



| Atomic Appli | ation Download                                         |
|--------------|--------------------------------------------------------|
| Application: | NoName.ato                                             |
| Size:        | 42 bytes (7%)                                          |
| Drive:       | Generic SDM / MD                                       |
| ld:          | 1                                                      |
| Interface:   | Serial at 57600 baud                                   |
| Update driv  | e parameters & user variables                          |
| Wi<br>ap     | ndow to transfer the program<br>plication to the drive |

# PC environment configuration

#### Other utility windows:

| IDE Settings<br>Enable Application Auto Save<br>Create Application Backup Copy | CAN Interface Settings<br>CAN Board: DXAT TinCAN CAN Board Address: 0 | Window to  |
|--------------------------------------------------------------------------------|-----------------------------------------------------------------------|------------|
| Font Size: 8                                                                   | CAN Baud Rate: 125K                                                   | Parameters |
| Communication Interface                                                        | RS232 Interface Settings                                              |            |
| <ul> <li>RS232 Interface (MODBUS)</li> </ul>                                   | Serial Port: COM1 💙                                                   |            |
| CAN Interface (CANopen)                                                        | Serial Baud Rate: 57600 🗸                                             |            |
| Drive Settings                                                                 |                                                                       |            |
|                                                                                | er: Generic SDM / MD                                                  |            |